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D D5824 Pages: 2

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## APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

FIFTH SEMESTER B.TECH DEGREE EXAMINATION, APRIL 2018

Course Code: EE311

## Course Name: ELECTRICAL DRIVES & CONTROL FOR AUTOMATION (AU, ME)

Duration: 3 Hours Max. Marks: 100

### PART A Marks Answer any three full questions, each carries 10 marks 1 Give the classification of the DC generators depending upon their field excitation (5) with simple sketches. b) An 8-pole wave connected DC generator has 1000 armature conductors and flux (2)per pole is 0.035Wb. At what speed must it be driven to generate 500V? Draw the open circuit characteristics of a DC shunt generator and define critical **(3)** resistance. 2 a) A DC shunt generator having a terminal voltage of 250V delivers a load current of (2) 195A. The armature and shunt field resistances are 0.05 ohm and 50 ohms respectively. Calculate: i) Armature current ii) Generated emf in armature. b) With the help of a neat circuit diagram explain the procedure for obtaining the (6)internal and external characteristics of a DC shunt generator. c) Write any two methods for compensating the effects of armature reaction in DC (2)generators. 3 Explain how the torque is developed in a DC motor? **(3)** (3)

- b) What is meant by back emf in DC motors? A 230 V DC shunt motor takes 32 Amp at full load. Find the back emf on full load if resistances of motor armature and shunt field windings are 0.2 ohm and 115 ohms respectively.
- Give the classification of DC motors with applications. (4)
- 4 Draw the power conversion stages of a DC motor.
  - With a neat figure explain the method for conducting load test in a DC shunt (6)motor.
  - c) Why starter is necessary in a DC motor? (2)

### PART B

## Answer any three full questions, each carries 10 marks

- 5 A 40 KVA single phase transformer has 400 turns on the primary and 100 turns on (3) the secondary. The primary is connected to 2000 V, 50 hz supply. Determine:
  - The Secondary voltage on open circuit
  - ii) Maximum value of flux.

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- b) Draw the phasor diagram of a single-phase transformer with inductive load and (2)mark each phasor clearly.
- c) What is an auto transformer? With suitable derivations, prove that there is saving (5) of copper in auto transformer compared to ordinary transformer.
- 6 Obtain the approximate equivalent circuit With respect to low voltage side of a (6) given 200/2000 V single phase 30 KVA transformer having the following test results.
  - O.C test: 200V, 6.2A, 360W on L.V. side S.C test:- 75 V, 18A, 600W on H.V side
  - b) Define the all-day efficiency of a distribution transformer. What is its significance? (2)

D		D5824 Pages: 2	Pages: 2	
	c)	What are instrument transformers? Give its types.	(2)	
7	a)	With neat sketch, explain the development of rotating magnetic field in a three- phase induction motor.	(5)	
	b)	Define slip and draw the torque slip characteristics of a three-phase induction motor.	(2)	
	c)	A three phase induction motor has 2 poles and is connected to 400 V, 50 hz supply. Calculate the actual rotor speed and rotor frequency when slip is 4%.	(3)	
8	a) b)	Draw the equivalent circuit per phase of a three-phase induction motor and explain.  A 40 KW 6 pole three phase induction motor delivers full load output at 950 rpm at 0.85p.f when connected to a 500 volt, 50 hz supply. Friction and windage losses equals 1.5KW and stator losses are 1.8KW. Determine for this load:  i) Total copper loss  ii) Efficiency.	(5) (5)	
		PART C		
		Answer any four full questions, each carries 10 marks		
9	a)	Describe principle of working of single phase induction motors with neat sketches.	(5)	
	b)	With suitable graphs explain the method to determine voltage regulation of an alternator by EMF method.	(5)	
10	a)	Derive the emf equation of an alternator.	(3)	
	b)	Write a note on the starting of synchronous motors.	(3)	
	c)	Draw and explain the 'V' curves of a synchronous motor.	(4)	
11	a)	A three-phase star connected alternator is rated at 1600 KVA, 13500 Volt. The armature resistance and synchronous reactance are 1.5 and 30 ohms respectively per phase. Calculate the percentage voltage regulation for a load of 1820 KW at 0.8 leading p.f.	(4)	
	b)	What are universal motors? Explain their working.	(3)	
		Define distribution factor and pitch factor of an alternator.	(3)	
12	a)	Draw the schematic diagram of a variable reluctance motor and explain its working.	(7)	
	b)	What is micro stepping? Determine the step angle of a variable reluctance stepper motor with 12 teeth in stator and 8 rotor teeth.	(3)	
13	a)	Draw the stepper motor characteristics and explain. Also list the applications of stepper motors.	(5)	
	b)		(5)	
14	a)	Give the two major classification of general control systems and explain them with suitable block diagrams. Give examples for each type.	(6)	
	b)	Write a note on different types of controllers for automation.  ****	(4)	
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	Total Pages:	2
Reg N	o.: Name:	-
	APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY FIFTH SEMESTER B.TECH DEGREE EXAMINATION, DECEMBER 2017	
	Course Code: EE311	
Cot	rse Name: ELECTRICAL DRIVES & CONTROL FOR AUTOMATION (AU,	ME)
Max.	Marks: 100 Duration: 3	Hour
	PART A	
	Answer any three full questions, each carries 10 marks.	Mark
1 a	Derive an expression for the e.m.f generated in a d.c machine.	(4)
t	) What is meant by armature reaction? How does it will affect the main field flux?	(2)
C	List out the different methods of excitation. Explain.	(4)
2 a	A d.c shunt generator operating at 850rpm is given below	(8)
	Eg(V): 12 40 102 176210 240 256	
	I <sub>f</sub> (A): 0 0.5 1 2 345	
	The machine has 6 poles. The type of winding is lap. The number of conductors	
	in the armature is 540. http://www.ktuonline.com	
	i) Calculate residual flux per pole.	
	ii) The no load e.m.f for a total shunt field resistance of $120\Omega$ .	
	iii) The critical field resistance of the field circuit.	
	iv) The critical speed for the shunt field resistance of $120\Omega$ .	
ŀ	Define critical speed and critical field resistance of a d.c shunt generator.	(2)
3 a	Derive an expression for the electromagnetic torque developed in a d.c motor.	(2)
ŀ	A d.c shunt motor runs at 1300rpm on no-load drawing 5A from 220V mains. Its	(8)
	armature and field resistance are $0.24\Omega$ and $110\Omega$ respectively. When loaded	
	.the motor draws 60A from the mains. Calculate the speed when the motor is	
	loaded. Assume that the armature reaction demagnetizes the field by 3%. Also	
	calculate the internal torque developed at no load and on load. What is the motor	
	shaft torque at load?	
4 a	Derive the speed-torque characteristics of a d.c shunt and d.c series motor.	(4)
ł	) What are the losses occurring in a d.c motor and how do they vary with load current?	(3)
c	Why a starter is required for starting a d.c motor?	(3)
	PART B	
	Answer any three full questions, each carries 10 marks.	
5 a	Derive the e.m.f equation of a single phase transformer.	(4)
t	) Draw the phasor diagram of a 1-phase transformer at no load and derive the	(4)
	equivalent circuit.	-
c	Explain the difference between an ideal transformer and an actual transformer	(2)
6 a	What are the losses produced in a transformer and derive the condition for	(4)

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### http://www.ktuonline.com D7096 D maximum efficiency. b) A 40kVA single phase transformer has iron loss of 450W and full load copper (4) loss of 850W. If the pf of the load is 0.8 calculate: i) The full load efficiency. ii) The maximum efficiency. iii) The load at which maximum efficiency occur. c) Write short notes on instrument transformers. (2)7 a) Explain the principle of operation of a 3-phase induction motor (4) b) Differentiate between squirrel cage and slipring induction motor. (2)Write short notes on torque-slip characteristics of a 3-phase induction motor (4) 8 a) Explain no load and blocked rotor test on a 3-phase induction motor and derive (4) the equivalent circuit parameters. b) What is meant by circle diagram of a induction motor? What are the information (1)that can be obtained from the circle diagram? Explain with the help of neat diagram the working of any two methods of (5)starting a 3-phase induction motor. PART C Answer any four full questions, each carries 10 marks. 9 Derive the e.m.f equation of an alternator. (3) What is meant by regulation of an alternator? (1) How can you determine the regulation of an alternator by e.m.f method? (6) Explain. 10 Explain the principle of operation of 1-phase induction motor. (2)b) Explain the pitch factor and distribution factor of an alternator. (4) What is a universal motor? What are the applications of this type of motors? (4) 11 Why synchronous motor has no net starting torque. (2) a) b) Explain the methods of starting synchronous motor (6)What is synchronous condenser? (2)c) 12 a) With a neat sketch, explain the working of a permanent magnet stepper motor. (7)b) List out the classification of stepper motor and compare them. (3) a) Draw and explain the torque-speed characteristics of stepper motor. 13 (3) b) Write short notes on servo control and digital controllers. (7)14 a) What is machine tool controller? (3)

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b) With neat diagram explain programmable logic controllers.

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