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B

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY
THIRD SEMESTER M.TECH DEGREE EXAMINATION, July 2018

Branch:

Electronics and Communication Engineering

Stream(s): -

Signal Processing

Course Code & Name:

01EC 7315: Computer Vision

Answer any two full questions from each part

Limit answers to the required points.

Max. Marks: 60

Duration: 3 hours

PART A

- | | | | |
|----|----|---|---|
| 1. | a. | Derive the perspective projection equation. State the assumptions used. | 7 |
| | b. | Prove that parallel lines when imaged, converge at a point. | 2 |
| 2. | | Explain in detail the steps for computing scale-invariant feature transform (SIFT). | 9 |
| 3. | a. | Explain the use of Hough transform for line detection. | 5 |
| | b. | Explain Harris corner point detector. | 4 |

PART B

- | | | | |
|----|----|--|---|
| 4. | | Explain in detail the steps involved in structure from motion (SFM) method for 3D reconstruction. | 9 |
| 5. | a. | What is aperture problem in optical flow? | 2 |
| | b. | Derive the Horn-Schunck algorithm for computation of optical flow. | 7 |
| 6. | a. | Derive the optical flow constraint equation. | 3 |
| | b. | Prove that optical flow obtained using Lucas-Kanade algorithm is the least squared solution of optical flow constraint equation. | 6 |

PART C

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|----|----|---|---|
| 7. | a. | Define shape from shading. | 3 |
| | b. | Derive an equation for surface normals posing shape from shading as an optimization problem. | 6 |
| 8. | a. | Explain in detail the steps for object detection using histogram of oriented gradients (HOG). | 8 |

- b. Explain any two measures used to evaluate the performance of an object detection algorithm <http://www.ktuonline.com> 4
- 9. a. Differentiate face detection and face recognition problems in computer vision. 4
- b. Explain the Eigen faces method for face recognition in images. 8